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# A note: Every homogeneous difference equation of degree one admits a reduction in order 

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#### Abstract

Every difference equation $x_{n+1}=f_{n}\left(x_{n}, x_{n-1}, \ldots, x_{n-k}\right)$ of order $k+1$ with each mapping $f_{n}$ being homogeneous of degree 1 on a group $G$ is shown to be equivalent to a system consisting of an equation of order $k$ and a linear equation of order 1 .


Keywords: order reduction; homogeneous; degree 1; non-autonomous

Let $G$ be a nontrivial group and consider the non-autonomous difference equation of order $k+1$

$$
\begin{equation*}
x_{n+1}=f_{n}\left(x_{n}, x_{n-1}, \ldots, x_{n-k}\right), \quad n=0,1,2, \ldots \tag{1}
\end{equation*}
$$

where $x_{n} \in G$ and $f_{n}: D \rightarrow G$ for every $n$. The domain $D \subset G^{k+1}$ is such that the projection of $D$ into each of the $k+1$ coordinates equals $G$ and that $F_{n}(D) \subset D$ i.e. $D$ is invariant under the unfolding $F_{n}\left(u_{0}, \ldots, u_{k}\right)=\left(f_{n}\left(u_{0}, \ldots, u_{k}\right), u_{0}, \ldots, u_{k-1}\right)$ of $f_{n}$ for every $n$. Equation (1) recursively generates a solution or orbit $\left\{x_{n}\right\}_{n=-1}^{\infty}$ in $G$ from a set of initial values $x_{0}, x_{-1}, \ldots, x_{-k}$ in $G$.

The group structure provides a suitable context for our main result, but in most applications $G$ is a substructure of a more complex object such as a vector space or an algebra possessing a metric topology relative to which the mappings $f_{n}$ are continuous. In such cases, each $f_{n}$ may be defined on the ambient structure as long as the invariance condition $f_{n}(D) \subset G$ holds for all $n$.

We call a function $f: D \rightarrow G$ homogeneous of degree 1 (or HD1) on $D$ relative to $G$ if

$$
\begin{equation*}
f\left(t u_{0}, \ldots, t u_{k}\right)=t f\left(u_{0}, \ldots, u_{k}\right) \text { for all } t, u_{i} \in G, i=0, \ldots, k \tag{2}
\end{equation*}
$$

If each $f_{n}$ in (1) is HD1 on $D$ then we say that equation (1) is homogeneous of degree 1.
The case $k=1$ for equation (1) is discussed in [3] where the second-order equation $x_{n+1}=f_{n}\left(x_{n}, x_{n-1}\right)$ with HD1 maps $f_{n}$ is seen to be equivalent to a system of two first-order equations

$$
u_{n+1}=h_{n}\left(u_{n}\right), \quad v_{n+1}=v_{n} u_{n+1}
$$

The next theorem extends this result to an arbitrary integer $k \geq 1$. For further comments on homogeneous functions and their abundance on groups we refer to [3]; these comments extent to any number of variables.

[^0]TheOrem. Let $G$ be a nontrivial group. If $f_{n}$ is HD1 relative to $G$ for $n \geq 1$ then equation (1) is equivalent to the following system of equations

$$
\begin{aligned}
& r_{n+1}=f_{n}\left(1, r_{n}^{-1},\left(r_{n-1} r_{n}\right)^{-1}, \ldots,\left(r_{n-k+1} \cdots r_{n-1} r_{n}\right)^{-1}\right) \\
& s_{n+1}=s_{n} r_{n+1}
\end{aligned}
$$

Note that the first difference equation above has order $k$ and the second is linear of order one in $s_{n}$.

Proof. For each solution $\left\{x_{n}\right\}_{n=-k}^{\infty}$ of (1) define $r_{n}=x_{n-1}^{-1} x_{n}$ for each $n=-k+1,-k+2, \ldots$ Then $x_{n+1}=x_{n} r_{n+1}$ and

$$
\begin{aligned}
r_{n+1} & =x_{n}^{-1} x_{n+1}=x_{n}^{-1} f_{n}\left(x_{n}, x_{n-1}, x_{n-2}, \ldots, x_{n-k}\right)=f_{n}\left(1, x_{n}^{-1} x_{n-1}, x_{n}^{-1} x_{n-2}, \ldots, x_{n}^{-1} x_{n-k}\right) \\
& =f_{n}\left(1, x_{n}^{-1} x_{n-1},\left(x_{n}^{-1} x_{n-1}\right)\left(x_{n-1}^{-1} x_{n-2}\right), \ldots,\left(x_{n}^{-1} x_{n-1}\right)\left(x_{n-1}^{-1} x_{n-2}\right) \cdots\left(x_{n-k+1}^{-1} x_{n-k}\right)\right) \\
& =f_{n}\left(1, r_{n}^{-1},\left(r_{n-1} r_{n}\right)^{-1}, \ldots,\left(r_{n-k+1} \cdots r_{n-1} r_{n}\right)^{-1}\right) .
\end{aligned}
$$

It follows that $\left\{r_{n}\right\}_{n=-k+1}^{\infty}$ is a solution of the first equation so that $\left\{\left(r_{n}, s_{n}\right)\right\}_{n=-k+1}^{\infty}$ is a solution of the system with $s_{n}=x_{n}$ for $n=-k+1,-k+2, \ldots$

Conversely, let $\left\{\left(r_{n}, s_{n}\right)\right\}_{n=-k+1}^{\infty}$ be a solution of the system. Then, $\left\{r_{n}\right\}_{n=-k+1}^{\infty}$ is a solution of the first equation. Choose $x_{-k} \in G$ and set $x_{n}=s_{n}$ for $n=-k+1,-k+2, \ldots$ Then, $x_{n+1}=s_{n+1}=x_{n} r_{n+1}$ so that

$$
\begin{aligned}
x_{n+1} & =x_{n} f_{n}\left(1, r_{n}^{-1},\left(r_{n-1} r_{n}\right)^{-1}, \ldots,\left(r_{n-k+1} \cdots r_{n-1} r_{n}\right)^{-1}\right) \\
& =f_{n}\left(x_{n}, x_{n}\left(x_{n-1}^{-1} x_{n}\right)^{-1}, x_{n}\left(x_{n-2}^{-1} x_{n}\right)^{-1} \ldots, x_{n}\left(x_{n-k}^{-1} x_{n}\right)^{-1}\right) \\
& =f_{n}\left(x_{n}, x_{n-1}, x_{n-2}, \ldots, x_{n-k}\right) .
\end{aligned}
$$

It follows that the sequence $\left\{x_{n}\right\}_{n=-k}^{\infty}$ is a solution of (1).

Remarks 1. (a) The system in the above Theorem can be solved explicitly in terms of a solution $\left\{r_{n}\right\}_{n=-k+1}^{\infty}$ of the first equation as follows:

$$
\begin{equation*}
s_{n}=s_{0} r_{1} r_{2} \cdots r_{n} \quad n=1,2,3, \ldots \tag{3}
\end{equation*}
$$

Thus for HD1 functions, the above theorem essentially reduces the study of equation (1) with order $k+1$ to that of the first equation of the system which has order $k$. In the additive case, (3) takes the form

$$
\begin{equation*}
s_{n}=s_{0}+r_{1}+r_{2}+\cdots+r_{n} \tag{4}
\end{equation*}
$$

(b) We can quickly construct the first equation of the system in the above Theorem directly from (1) in the HD1 case by making the substitutions

$$
\begin{equation*}
1 \rightarrow x_{n}, \quad\left(r_{n-i+1} \cdots r_{n-1} r_{n}\right)^{-1} \rightarrow x_{n-i} \text { for } i=1,2, \ldots, k \tag{5}
\end{equation*}
$$

Recall that 1 represents the group identity. In the additive case, (5) takes the form

$$
\begin{equation*}
0 \rightarrow x_{n}, \quad-r_{n}-r_{n-1} \cdots-r_{n-i+1} \rightarrow x_{n-i} \quad \text { for } i=1,2, \ldots, k \tag{6}
\end{equation*}
$$

The number of different types of HD1 equations is unlimited. Previous studies involving HD1 equations implicitly use the idea behind the theorem above to reduce second-order equations to first-order ones; see e.g. [1]. Here, we discuss a few equations with orders $>2$ to illustrate the theorem above and some associated concepts.

Example 1. Consider the autonomous rational difference equation

$$
\begin{equation*}
x_{n+1}=x_{n}\left(\frac{a x_{n-k+1}}{x_{n-k}}+b\right), \quad a, b>0, a+b \neq 1 \tag{7}
\end{equation*}
$$

With positive initial values, this equation is clearly HD1 relative to the multiplicative group $G$ of positive real numbers $(0, \infty)$. The Theorem above states that equation (7) which has order $k+1$ can be reduced to an equation of order $k$ using (5) as follows:

$$
\begin{equation*}
r_{n+1}=1\left(\frac{a\left(r_{n-k+2} \cdots r_{n-1} r_{n}\right)^{-1}}{\left(r_{n-k+1} \cdots r_{n-1} r_{n}\right)^{-1}}+b\right)=a r_{n-k+1}+b \tag{8}
\end{equation*}
$$

Using the linear (non-homogeneous) equations (8) and (3) it can be shown easily that if $a+b<1$ then all solutions of equation (7) converge to zero, eventually monotonically and that if $a+b>1$ then all solutions of equation (7) converge to $\infty$, eventually monotonically.

Remarks 2. (a) Example 1 can be extended to the non-autonomous equation

$$
x_{n+1}=x_{n}\left(\frac{a_{n} x_{n-k+1}}{x_{n-k}}+b_{n}\right)
$$

whose order-reduced form is $r_{n+1}=a_{n} r_{n-k+1}+b_{n}$. In particular, if $a_{n} \rightarrow a$ and $b_{n} \rightarrow b$ with $a, b$ as above, then the conclusions of example 1 are essentially unchanged.
(b) Note that an HD1 equation on a group $G$ cannot have any isolated fixed points in $G$. But after reduction of order, the resulting equation is usually not HD1 and often has isolated fixed points. This is seen both in examples 1 and 2 below. Thus, the theorem above is a necessary 'starter' for analyzing HD1 equations, because conventional methods of analysis (e.g., linearization, semicycles, etc.) can often be applied only to the lower order, non-HD1 equation.
(c) System (2) is a special type of semiconjugate factorization; see [4].

Example 2. The difference equation

$$
\begin{equation*}
x_{n+1}=x_{n}+\frac{b}{a+x_{n-j}-x_{n-k}}, \quad a, b>0, \quad k \geq 1, \quad 0 \leq j \leq k-1 \tag{9}
\end{equation*}
$$

is HD1 relative to the additive group $\mathbb{R}$. Using (6) we order-reduce it to

$$
\begin{equation*}
r_{n+1}=\frac{b}{a+r_{n-j}+r_{n-j+1}+\cdots+r_{n-k+1}}, \quad r_{n}=x_{n}-x_{n-1} . \tag{10}
\end{equation*}
$$

Initial values satisfying $x_{0}>x_{-1}>\ldots>x_{-k}$ result in $r_{0}, \ldots, r_{-k+1}>0$. This implies that $r_{n}>0$ for $n \geq 1$, so the corresponding solution $x_{n}$ of (9) is increasing and eventually positive since by (4) $x_{n}=x_{0}+\sum_{j=1}^{n} r_{j}$. Equation (10) has known properties; substituting $t_{n}=b / r_{n}$ transforms (10) into the more familiar $t_{n+1}=a+b \sum_{i=j}^{k-1} 1 / t_{n-j}$. It is shown in [2] that all positive solutions of this version of (10) converge to its unique positive fixed point $L=\left(a+\sqrt{a^{2}+4 b(k-j)}\right) / 2$. Thus a straightforward argument shows that $x_{n} / n \rightarrow b / L$ as $n \rightarrow \infty$; i.e. $x_{n}$ converges to $\infty$ asymptotically as $(b / L) n$.

Example 3. This example illustrates a situation where (1) and its order-reduction are both HD1, although with respect to different groups. We examine the third order equation

$$
\begin{equation*}
x_{n+1}=x_{n}+\frac{a\left(x_{n}-x_{n-1}\right)^{2}}{x_{n-1}-x_{n-2}}, \quad a>0 \tag{11}
\end{equation*}
$$

Relative to the additive group $\mathbb{R}$, this equation is HD1 and reducible to $r_{n+1}=$ $a r_{n}^{2} / r_{n-1}$ with $r_{n}=x_{n}-x_{n-1}$. Note that $r_{n} \neq 0$ for $n \geq 1$ if initial values satisfy

$$
\begin{equation*}
x_{0}, x_{-2} \neq x_{-1} \tag{12}
\end{equation*}
$$

Relative to the multiplicative group of all nonzero real numbers, the second-order equation above is HD1 and reducible to the first-order linear equation $t_{n+1}=a t_{n}$ with $t_{n}=r_{n} / r_{n-1}$. Now using (3) and (4) we obtain the following formula for solutions of (11) subject to (12):

$$
x_{n}=x_{0}+r_{0} \sum_{k=1}^{n} t_{0}^{k} a^{k(k+1) / 2}, \quad t_{0}=\frac{r_{0}}{r_{-1}}=\frac{x_{0}-x_{-1}}{x_{-1}-x_{-2}} .
$$

This representation and standard analysis establish the following types of behavior for (11): given the increasing nature of $x_{n}$, if $a>1$ then all positive solutions subject to (12) converge to $\infty$; if $a<1$ then all positive solutions subject to (12) converge to a finite limit that depends on the initial values. If $a=1$ then bounded and unbounded solutions coexist: if $x_{0}+x_{-2}<2 x_{-1}$ then $\lim _{n \rightarrow \infty} x_{n}=x_{0}+\left(x_{0}-x_{-1}\right)^{2} /\left(2 x_{-1}-x_{-2}-x_{0}\right)$ but if $x_{0}+x_{-2} \geq 2 x_{-1}$ then $x_{n} \rightarrow \infty$ as $n \rightarrow \infty$.

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